

Modeling and replicating statistical topology and evidence for CMB nonhomogeneity

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Under the banner of “big data,” the detection and classification of structure in extremely large, high-dimensional, data sets are two of the central statistical challenges of our times. Among the most intriguing new approaches to this challenge is “TDA,” or “topological data analysis,” one of the primary aims of which is providing nonmetric, but topologically informative, preanalyses of data which make later, more quantitative, analyses feasible. While TDA rests on strong mathematical foundations from topology, in applications, it has faced challenges due to difficulties in handling issues of statistical reliability and robustness, often leading to an inability to make scientific claims with verifiable levels of statistical confidence. We propose a methodology for the parametric representation, estimation, and replication of persistence diagrams, the main diagnostic tool of TDA. The power of the methodology lies in the fact that even if only one persistence diagram is available for analysis—the typical case for big data applications—the replications permit conventional statistical hypothesis testing. The methodology is conceptually simple and computationally practical, and provides a broadly effective statistical framework for persistence diagram TDA analysis. We demonstrate the basic ideas on a toy example, and the power of the parametric approach to TDA modeling in an analysis of cosmic microwave background (CMB) nonhomogeneity.

persistence diagrams | Gibbs measures | topological data analysis | statistical topology | CMB nonhomogeneity

As a consequence of the current explosion in size, complexity, and dimensionality of data sets, there has been a growing need for the development of powerful but concise summary statistics and visualization methods that facilitate understanding and decision-making. A singularly novel approach, which has been particularly promising in areas as widespread as biology and medicine (1–3), neurophysiology, (4), cosmology (5, 6), and materials science (7), has been via the application of the powerful, and rather abstract, concepts of algebraic topology to develop what generally now falls under the label of “topological data analysis” (TDA). While approaching complex data from a topological viewpoint is not entirely new—it underlies Tukey’s “Exploratory data analysis” of the 1960s (8) and the more recent approach by Friston and coworkers to brain imaging data (9)—TDA differs from all its forebears in its sophisticated exploitation of recent developments in computational topology. In particular, much of TDA has become almost synonymous with an analysis based on some version of persistent homology (10–12), represented visually as barcodes, persistence diagrams (PDs), or related representations (13–17).

With relatively few exceptions, notably refs. 17–22 (see additional citations in *SI Appendix, Homology and Persistent Homology*) TDA has not used statistical methodology as part of its approach, and, as a consequence, has typically been unable to associate clearly defined levels of statistical significance to its discoveries. While there may be a variety of reasons for this, one of the main obstacles to doing so is that the mathematical challenges involved in computing the statistical distributions of topological quantifiers have so far proven to be intractable. This is despite the fact that the measure-theoretic issues involved

in defining probability measures which support notions such as expectations, variances, percentiles, and conditional probabilities have been effectively solved, for example, refs. 23–25.

One approach adopted by refs. 18–20 and others to circumvent these difficulties has been to reduce persistence diagrams to a single test statistic, often related to bottleneck norms, and then to adopt standard statistical resampling methods to analyze this statistic. If multiple diagrams are available, then the resampling can be done on them. However, since TDA is typically used in areas of very large data sets, the availability of replicates is rare, and consequently this approach is impracticable in most applications. An alternative approach is to (sub)sample points from the persistence diagram, and compute statistics on the subsamples. The problem with this approach, however, is that the true random object here is the full persistence diagram, and thus it is often unclear what is the precise meaning of the statistics produced this way.

We introduce an approach, based on generating a sequence of persistence diagrams which has similar statistical properties to those of the one generated by the data. The individual concepts underlying the method are not difficult, and follow a number of clearly defined stages. First, a parametric model is adopted that is sufficiently flexible to model an extremely wide class of persistence diagrams. The model we use is a class of Gibbs distributions, since these have a long history of success in modeling point sets (ref. 26 and its bibliography), which, essentially, is what a persistence diagram is. Having estimated parameters, we then exploit the fact that Gibbs distributions lend themselves to simulation by Markov chain Monte Carlo (MCMC) methods, and apply MCMC to produce a simulated sequence of diagrams.

Significance

Under the general heading of “topological data analysis” (TDA), the recent adoption of topological methods for the analysis of large, complex, and high-dimensional data sets has established that the abstract concepts of algebraic topology provide powerful tools for data analysis. However, despite the successes of TDA, most applications have lacked formal statistical veracity, primarily due to difficulties in deriving distributional information about topological descriptors. We present an approach, Replicating Statistical Topology (RST), which takes the most basic descriptor of TDA, the persistence diagram, and, using models based on Gibbs distributions and Markov chain Monte Carlo, provides replications of it. These allow for formal statistical hypothesis testing, without requiring costly, or perhaps intrinsically unavailable, replications of the original data set.

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Restricting ourselves, for reasons to become clear soon, to $\mathcal{X} = \mathbb{R} \times \mathbb{R}_+$, define, for $x = (x^{(1)}, x^{(2)}) \in \mathcal{X}$,

$$\sigma_H^2 = \sum_{x \in \tilde{x}_N} \left(x^{(1)} - \bar{x}^{(1)} \right)^2, \quad \sigma_V^2 = \sum_{x \in \tilde{x}_N} \left(x^{(2)} \right)^2,$$

where $\bar{x}^{(1)} = N^{-1} \sum_{i=1}^N x_i^{(1)}$.

We now define a Hamiltonian, at effective interaction distance δ , up to cluster size $K \geq 0$, and, with interaction parameter $\Theta = (\theta_H, \theta_V, \theta_1, \dots, \theta_K)$, as

$$H_{\delta, \Theta}^K(\tilde{x}_N) = \theta_H \sigma_H^2 + \theta_V \sigma_V^2 + \sum_{k=1}^K \delta^{-2} \theta_k \mathcal{L}_{\delta, k}(\tilde{x}_N). \quad [3]$$

The parameters here all have clear meanings. The horizontal spread about the mean of the points is controlled by σ_H^2 , and the vertical spread is controlled by σ_V^2 [not centered because of the assumed nonnegativeness of the components $x^{(2)}$]. Each θ_k is a measure of energy density, controlling the probability of clusters of size $k+1$, with $\theta_k < 0$ favoring such clusters, and $\theta_k > 0$ lowering their probabilities. As noted in *SI Appendix, Probability Models for Persistent Diagrams*, working with energy densities rather than absolute energies (i.e., without the δ^{-2} factor in Eq. 3) leads to more-robust numerical procedures.

Now, given a PD $\tilde{B} = \{(b_i, d_i)\}_{i=1}^N$, define a new set of N points $\tilde{x}_N = \{x_i\}_{i=1}^N$, with $x_i^{(1)} = d_i$ and $x_i^{(2)} = b_i - d_i$. This (invertible) transformation has the effect of moving the points in Fig. 1 downward, so that the diagonal line projects onto the horizontal axis, but still leaves a visually informative diagram, which we shall call the projected PD (PPD). The statistical model we take for PPDs is a Gibbs distribution Eq. 2 with Hamiltonian Eq. 3.

While this may seem a rather arbitrary form for the distribution of a PPD, there are a number of facts justifying it. The first is the trivial observation that any multivariate distribution can be written in the form of Eq. 2, simply by taking $H_\Theta \equiv -\ln(\varphi_\Theta)$ and $Z_\Theta = 1$. Moreover, “cluster expansions” of this form have been successfully used in statistical mechanics for the best part of a century as a basic approximation tool in the study of particle systems. More specifically, for the model to be rich enough for TDA, we need to choose the Hamiltonian from a parameterized family that comes close to spanning all “reasonable” functions on PPDs. However, we know from ref. 29 that the ring of algebraic functions on the space of PPDs is spanned by a family of monomials closely related to functions of the form of Eq. 3. Finally, there is the issue, discussed in detail in *SI Appendix, Probability Models for Persistent Diagrams*, that we will often use these distributions not as exact models for PPDs but rather as a tool in a perturbative analysis. In these cases, the convenience of the models is more important than whether or not they provide a perfect fit to PPD data.

The determination of δ depends on the number and spread of the points in the PD. In practice, theoretical results (compare the reviews in refs. 30 and 31) suggest taking δ of the form

$$\delta = \frac{\delta^*}{N^{\alpha_{k,d}}} \max \left(\max |x_i^{(1)} - x_j^{(1)}|, \max |x_i^{(2)} - x_j^{(2)}| \right), \quad [4]$$

where $\alpha_{0,d} = 1/d$, $\alpha_{k,d} = k/(k+1)d$ for $k \geq 1$, d is the dimension of the data underlying the PD, and δ^* is a data-independent tuning parameter. The terms inside the brackets in Eq. 4 scale for the order of magnitude of the data, which is unimportant topologically. (For cases for which d is unknown, setting $d = 2$ seems to work in practice, merely leading to larger than usual values of δ^* , as does ignoring the fine structure of $\alpha_{k,d}$ and taking it to be $N^{-1/2}$, as a global default.)

Pseudolikelihood. Given H_Θ as a parametric model, we now turn to the estimation problem. Unfortunately, estimation of the

parameters by a method such as direct maximum likelihood is precluded by the fact that we don’t have an analytic form for Z_Θ , nor is there any way to compute it numerically in any reasonable time frame.

The standard way around this problem, which we adopt, is the pseudolikelihood approach (32, 33). This originated in the context of point cloud data with spatial dependence, which is, essentially, a description of a PD. In particular, it exploits the inherent spatial Markovianity of a Gibbs distribution to replace the overall probability of, in our case, a random PPD \tilde{X}_N by the pseudolikelihood

$$L_{\delta, \Theta}^K(\tilde{x}_N) \triangleq \prod_{x \in \tilde{x}_N} f_\Theta(x | \mathcal{N}_{\delta, K}(x)), \quad [5]$$

where $\mathcal{N}_{\delta, K}(x)$ denotes the points among the K nearest neighbors of x in \tilde{x}_N which are of distance no greater than δ from x . If no such points exist, then we take $\mathcal{N}_{\delta, K}(x) = \emptyset$. The conditional, local densities $f_\Theta(x | \mathcal{N}_{\delta, K}(x))$ are given by

$$\frac{\exp(-H_{\delta, \Theta}^K(x | \mathcal{N}_{\delta, K}(x)))}{\int_{\mathbb{R}} \int_{\mathbb{R}_+} \exp(-H_{\delta, \Theta}^K(z | \mathcal{N}_{\delta, K}(x))) dz^{(1)} dz^{(2)}}, \quad [6]$$

and the conditional Hamiltonians $H_{\delta, \Theta}^K(x | \mathcal{N}_{\delta, K}(x))$ by

$$\theta_H [x^{(1)} - \bar{x}^{(1)}]^2 + \theta_V (x^{(2)})^2 + \sum_{k=1}^K \delta^{-2} \theta_k \mathcal{L}_{\delta, k}(\mathcal{N}_{\delta, K}(x)).$$

Model Specification and Parameter Estimation. While it might be expected that PPDs originating from different physical phenomena might require quite different models, we have found, in all of the examples that we tried, that taking $K = 2$ or 3 in Eq. 3—so that the largest cluster size was 3 or 4—was both efficient and sufficient. If a lower K was appropriate, then the estimation procedure described above estimated the higher-order parameters θ_k as close to zero. In this case, using standard, automated statistical procedures such as AIC, BIC, etc. (cf. ref. 34), we often deleted the corresponding clusters from the Hamiltonian. Overall, we found the procedure not to be sensitive to either these small parameters or the specific procedure adopted for deleting them. After considerable experimentation, we found that working with all parameters appearing when $K = 3$, regardless of their absolute value, was the easiest thing to do. We also found that taking $K > 3$ did little to improve the simulation procedure, and typically led to manifestations of overfitting. In *SI Appendix, Probability Models for Persistent Diagrams*, we describe some of this experimentation, giving examples of when these models are, and are not, successful in fitting PDs.

RST and MCMC

We refer the reader to refs. 35 and 36 for technical background to this section, in which we describe a standard Metropolis–Hastings MCMC approach to replicating PDs. In particular, see ref. 35, section 10.3.3, in which the particular approach we take is called “Metropolis-within-Gibbs” and its properties are discussed.

Given a pseudolikelihood as in *Pseudolikelihood* (with known or estimated parameters), generating simulated replications of the associated point set via MCMC is not hard, but first we need some definitions.

First, given a \tilde{x}_N , define a “proposal distribution” $q(\cdot | \tilde{x}_N)$ as the bivariate Gaussian density, with mean vector and covariance matrix identical to the empirical mean and covariance of the points in \tilde{x}_N , but restricted to $\mathbb{R} \times \mathbb{R}_+$. Next, for two points $x, x^* \in \mathbb{R} \times \mathbb{R}_+$, define an “acceptance probability,” according to which we will replace $x \in \tilde{x}_N$ by x^* , leading to the updated PPD

\tilde{x}_N^* , as

$$\rho(x, x^*) = \min \left\{ 1, \frac{f_{\Theta}(x^* | N_{\delta, K}(x)) \cdot q(x | \tilde{x}_N^*)}{f_{\Theta}(x | N_{\delta, K}(x)) \cdot q(x^* | \tilde{x}_N)} \right\}.$$

[Note that integration in the denominator of f_{Θ} in Eq. 6 depends on x only through its neighborhood, and so cancellation in the ratio means that it does not enter into the computation of $\rho(x, x^*)$. This makes MCMC for pseudolikelihoods much more computationally feasible than for full likelihood models.]

The basic step of the algorithm, which describes the update of the point set $\tilde{x}_N = (x_1, \dots, x_N)$, is then *Algorithm 1*.

Algorithm 1. MCMC step updating diagram for \tilde{x}_N

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- 1: $k = 0$
 - 2: $k \leftarrow k + 1$
 - 3: Choose x^* according to $q(\cdot | \tilde{x}_N)$
 - 4: Compute $\rho(x_k, x^*)$
 - 5: Choose U a standard uniform variable on $[0, 1]$
 - 6: if $U < \rho(x_k, x^*)$, then set $x_k = x^*$
 - 7: if $k < N$ then go to Step 2
-

To obtain N approximately independent PPDs, we adopt a procedure dependent on parameters n_b , n_r , and n_R : Starting with the original PPD, run *Algorithm 1* for a burn-in period. Then, starting with the final PPD from the burn-in, run the algorithm a further n_b times, choosing the last output of this block of n_b iterations as the first simulated PPD. Repeat n_r times, each time starting with the most recently simulated PPD, namely, the output of the previous block. Finally, replicate the entire procedure n_R times, for a total of $n = n_r \times n_R$ simulated PPDs. The optimal choice of n_b , n_r , and n_R typically depends on the specific problem, and the behavior of the Markov chain being simulated. See *SI Appendix, Probability Models for Persistent Diagrams* for details and practical guidelines for choosing these parameters.

Given the collection of n simulated PPDs, we convert each PPD back to a regular PD with the mapping $x \rightarrow (x^{(1)} + x^{(2)}, x^{(1)}) = (b, d)$ of its component points, and write $\mathcal{S}(\tilde{B}) = \{\tilde{B}_1, \dots, \tilde{B}_n\}$ for the resulting collection of simulated PDs generated from \tilde{B} . These form the first-level output of the RST procedure.

The higher levels are driven by the specific application, but the basic idea is to compute simpler, real, vector, or function-valued statistics off the simulated PDs, and take their empirical distribution as an estimate of the true, underlying distribution of the statistic. The same statistic, computed off the original PD, can then be tested for statistical significance against this empirical distribution in standard fashion. Diagrammatically, treating persistence-based TDA as a sequence of three steps,

physical phenomenon \rightarrow PD \rightarrow analysis,

RST comes in at the second stage, providing additional information on the variation of PDs to feed into the analyst's preferred method. This is best described by example.

Examples

We treat two examples. One is a toy problem, for which the true situation is known, to see how and if RST works. The second studies the topology of CMB, and the analysis required is far more subtle. Details of both are given in *SI Appendix*. For both cases, we emphasize the point implied in the preceding paragraph, that our main interest is in the replication of the PDs, and not the particular method of statistical analysis following that.

Example 1: Two Circles. As a simple (but representative) test case, take a random sample from two circles, as in Fig. 1. Note that, while there are many points corresponding to the H_0 homol-

ogy, there are only three for H_1 . Furthermore, the H_1 points are all closer to the diagonal boundary, and less prominent. [These are common phenomena for barcodes, addressed theoretically in a number of studies (e.g., ref. 37).] Consequently, the RST procedure will not work for H_1 in this example. However, we do not know of, nor can imagine, any statistical procedure that can reach a meaningful conclusion based on so few points. (The procedures such as those described in refs. 18 and 19 require some form of replication, usually via a bootstrapping approach, of the original data set. This is precisely what we are trying to avoid.) On the other hand, a homology which has, at most, three generators is small enough to be investigated ad hoc, and statistical procedures are hardly needed.

However, there are certainly enough H_0 points in Fig. 1 to fit a spatial model. Before we do this, note that there are two points (at the top left) that we know to be significant, since we know, a priori, that the data come from points on two circles. However, there are a number of other points far away from the diagonal, and, were we ignorant of the true situation, it would not be clear whether they were significant or not.

Adopting the approach of RST, we estimated the parameters for a Gibbs distribution for the model with pseudolikelihood Eq. 5 for the H_0 data, taking $K = 3$. For three different scenarios, we generated 1,000 simulated PDs from this model, each with a burn-in period of 1,000 iterations, with (n_b, n_r, n_R) given by (500, 20, 50), (500, 40, 25), or (500, 100, 10).

Using these three sets of simulations, we computed a number of statistics, but report on only one set here: the order statistics of the distances of the points in the PD to the diagonal. Given the points (b_i, d_i) of the PD, these are T_j , the j th largest among the differences $|d_i - b_i|$, $j = 1, \dots, N$. Empirical distributions of the order statistics are then trivial to derive from the simulations of the PDs, and the order statistics calculated off the original PD can be compared with these. The results, for all three scenarios, showed that T_1 and T_2 were highly significant (the largest P value reached in any of the six cases was 0.003). The P values for T_3 were all in the range (0.036, 0.041), and so T_3 was marginally significant at the standard 5% level. In none of the three scenarios was T_4 significant. Details of the analysis and the results are given in *SI Appendix, Probability Models for Persistent Diagrams*. These include a comparison with the bootstrap, confidence interval-based techniques of ref. 18. Using the same kernel bandwidth for the density estimate Eq. 1 that we used, these techniques identified only one point in each of the H_0 and H_1 diagrams as significant, indicating an underlying set topologically equivalent to a single circle, but missing the second circle. A similar analysis, using the related techniques in ref. 19, identified one H_0 point but no H_1 points at all. Adopting a different bandwidth, however, identified two points in each diagram, when using the methods of ref. 18.

In summary, blindly applying RST to simulate PDs, and taking the simplest of all statistics, showed (correctly) strong statistical evidence for two connected components in the topological space (two circles) which generated the PD, with borderline (but misleading) evidence for a third component. Despite the fact that the PD has a number of points far from the diagonal, and quite close to the third-farthest point (Fig. 1), these were (correctly) considered statistically insignificant. Thus, in this toy example, with the simplest of statistical quantifiers, RST competes favorably with existing methodologies.

Example 2: CMB Nonhomogeneity. Current cosmological theory describes a phase of rapid inflation in the primordial universe roughly 10^{-35} s after its birth. Spontaneous quantum fluctuations in what was then a high-energy, uniform, pseudovacuum universe resulted in minute perturbations in its density field. Eventually, aided by gravitational amplification, these

here will open the door to developing a wide variety of (semiparametric) statistical methods for further applications of TDA.

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